Magic Wall (working title)

David Croft SCOPE Sessions, 18.08.2011





Electromagnetic Spectrum



Human Eye Model















It's not a Kinect (Damnit)

- Has built in IR laser projector
- Only outline needed, not depth
- Minimum range 1.2m, maximum range 3.5m
- Intrusive
- Proprietary connector
- 640×480 @ 30fps (only)
- Most functionality is within the Xbox
- Expensive (100€+)

Inaccurate even at short range



Camera

- Cheap
- Fast frame rate
- Good resolution
- "Hackable" to remove IR-blocking filter and add IR band-pass filter
- Cross-platform drivers

PlayStation Eye Camera

- 640x480 @ 60fps (320x240 @ 120fps)
- Free community-written drivers for Windows, Mac, Linux (from 2.6.29)
- Already in use for open source multi-touch tables
- IR hacking well documented
- Very cheap for its quality (15€)

Hacking the PS₃ Eye

- Get it open (hard!)
- Remove built-in IR-blocking filter
- Fully-exposed and developed camera film, or floppy disk, work OK as visible light filter
- Better: specialised IR band-pass filter
- Get it closed without smashing the CCD sensor (even harder!)











IR Bandpass Filter













Infrared Emission

- Filtered incandescent lamps
- "IR" heat lamps (but also heat and light, and expensive)
- Lasers
- LEDs



Infrared floodlight

- Contrast between wall and ambient IR requires powerful emitters
- Position behind viewers requires unusual angle
- Should scale well to larger areas
- Still looking for a good source

What wavelength?

- 850-875nm seems best with the cameras I tested
- Also the cheapest
- Minor visible red glow,
 but only if you look at the LEDs
- Filter will depend on this too



850nm

 Bleeds slightly into visible spectrum
 Doesn't seem visible on reflection – but need to test with a child!

Requirements

- OpenCV (Open Computer Vision) library
- Much useful but cryptic real-time computer vision functionality

Processing

- Simplified programming environment for visual artists
- My library
- Wraps all of the above.
- Will be released soon at www.davidc.net

Software Flow

Source

Source

Source Controls

Configuration			and the second	X
Source 3D C	alibration Thresh	old Blob Detection	Display Show	
<u>S</u> ource	Local Camera	-		
Device	PS3Eye Camera	-		
Requested Size	320 wide by	240 high		
Free <u>z</u> e input l	frame			
				_

Calibration

3D Calibration

- Camera and projector are not at the exact same position
- Lenses and FOV are different anyway
- Need to recalibrate so that the final projected image lines up with bodies

3D Calibration

- Similar principle to touchscreen calibration, but in 3D space
- Correlate points in both projector and camera space
- Naïve implementation ignores perspective, but is fast and sufficient for not
- OpenCV has calibration routines

Calibration – Source Image

Calibration – Control Points

Calibration - Output

Calibration Method

- Turn off floodlights
- IR LED on a stick

- Search for a single blob of a given size range
- Take the average of its centre of gravity over a period of time
- Repeat for other points
- Run calibration routine
- Then re-project each source frame

Calibration Markers

Calibration

Calibration Controls

Configuration	
Source 3D Calibratio	on Threshold Blob Detection Display Show
class net.davidc.intart.c	alibrate3d.TrivialCalibrator
Top left corner (A) Top right corner (B) Bottom left corner (C) Bottom right corner (D)	x $79 \div$ y $62 \div$ x $369 \div$ y $66 \div$ x $69 \div$ y $318 \div$ x $388 \div$ y $314 \div$
	Run Calibration Scene

Blur

Threshold

Blur and Threshold Controls

Configuration				*			and dependent	
Source 3E	Calibration	Thres	hold B	lob Detect	ion Di	isplay	Show	
Blur	0 5	10 15	20 25	30 35	40 45	5 50		
Threshold Type	Binary					-		
Value	1		10 XI	15				
Invert Thre	shold							

Classification

Blob Detection

Blob Filtering

Contour Approximation

Blob Detection Controls

Configuration		<u> </u>	
Source 3D Calibration Detection Filter Blob limit Min area	Threshold Blob Detection	Display Show	
Max area Approximation Contour Algorithm CV_CH	AIN_APPROX_SIMPLE		
Polygon Accuracy	Q		

Blob Tracking

Scene

Display Controls

	Configuration							-	X
1	Source 3D Calibra	ation	Y TR	reshold	Blob E	etection	Display	Show	
	L	ocal	Exte	rnal					
	Source	V	\bigcirc	V with	calibrat	ion points			
	Calibrated		\bigcirc						
	Blurred		\bigcirc						
	Threshold		0						
	Blobs (full accuracy)		0						
l	Blobs (approx)		0						
	Blobs (redrawn)		0	🗌 On s	ource	BBox			
				🗌 Min t	oox	🖌 IDs			
	Show	V	۲						
			0	lontage					
		_	_		_				

Frame: 1880. FP5: 1.02 fps capture, 4.71 fps update, 4.71 fps display. Particles: 322

Scene Controls

Source 3D Calibration Threshold Blob Detection Display Show Scene class net.davidc.intart.scenes.FlameScene	Source 3D Calibration Threshold Blob Detection Display Show cene class net.davidc.intart.scenes.FlameScene <	Config	uration	
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Example Scenes

- Spotlight
- **Glow**
- Image projection
- Shadow trail
- Flames

Example Scenes

- Video projection
- Insects/flocking
- Rain
- Beach ball game
- **•** Forest

Example Scenes

Develop a reference hardware design
 Finish and release software as open source
 Invite others to develop scenes

Next Steps

- Find better floodlights
- Improve, finish and optimise software
- Write more demos
- Turn it into a Processing library
- Release it as open source software with a hardware reference design
- Regions of interest
- Camera and projector tiling

Further information

 Documentation will appear over the next few weeks at www.davidc.net

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